

# U.S. Army Research Institute for the Behavioral and Social Sciences

**Research Report 1504** 

# Target Acquisition and Analysis Training System: Effects of Motion on Performance in the Combat Vehicle Identification (CVI) Training Program

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December 1988

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Major conclusions drawn from analyses of these data include the following:

- Motion (after repeated training) provides a small positive effect but does not appear to be an essential ingredient in learning ground-toground vehicle R&I using the Basic CVI Training Program. This is true for both training responsive and nontraining responsive soldiers.
- Short term retention of learned R&I skills is not improved when motion is included in the training. Kenney and the statement of the statemen

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**Education and Training** 

The Fort Hood Field Unit of the U.S. Army Research Institute (ARI) has developed a series of target recognition and identification (R&I) training programs and conducted related research as part of the research titled Target Acquisition and Analysis Training System (TAATS). Both Training and Doctrine Command (TRADOC) and Forces Command (FORSCOM) recognized the need for standardized R&I training and requested that ARI develop such programs. This work was performed for the Combined Arms Center (CAC), Fort Leavenworth, Kansas.

This research report examines whether R&I performance is enhanced by using moving target vehicle images (video tape) during Combat Vehicle Identification (CVI) training rather than static target vehicle images. It evaluates both the amount of material learned and the retention over time of this material. Inasmuch as R&I training done in the Army with the Basic CVI Program uses static target vehicle images (35mm slides), and training with motion uses video, the results have cost and training implications. Specifically, CVI training with moving (videotaped) images is projected to be more costly than training with static 35mm slide images.

These results were briefed on 19 October 1984, to LTC Harold Fritz, proponent for vehicle identification, and copies were provided to CAC, Fort Leavenworth.

EDGAR M. JOHNSON

TARGET ACQUISITION AND ANALYSIS TRAINING SYSTEM: EFFECTS OF MOTION ON PERFORMANCE IN THE COMBAT VEHICLE IDENTIFICATION (CVI) TRAINING PROGRAM

### **EXECUTIVE SUMMARY**

### Requirement:

The Target Acquisition and Analysis Training System (TAATS) research program was established to provide a framework for development of logically related training programs. The impetus for such a system was provided by a series of Human Resources Needs (HRN) requests dating from 1975 from both Training and Doctrine Command (TRADOC) and Force Command (FORSCOM). In 1980 an integrated series of training programs was planned in conjunction with the Army's proponent for vehicle recognition at the Combined Arms Center (CAC), Fort Leavenworth, Kansas. The first of the training programs was the Basic Combat Vehicle Identification (CVI) Training Program, produced in 1981 and adopted the same year by the Army as its standardized recognition and identification (R&I) training program (GTA 17-2-9).

Some researchers thought that motion would be an important addition to CVI training programs. These advocates felt that motion would add realism, increase soldier motivation to learn, and provide cues about the vehicles that would facilitate learning. The purpose of this research is to first explore the validity of the belief that using vehicles in motion (video tape) in the Basic CVI Training Program would improve performance over that achieved with static vehicles; and second, to determine whether motion differentially affects training responsive and non-training responsive performers.

### Procedure:

Data from the 85th Army Reserve Division (Tng), Arlington Heights, Illinois, were used to evaluate the effects of motion on performance immediately after repeated training and again, 18 hours after training. Soldiers ( $\underline{N}$ =120) were assigned to one of four conditions: circular motion, rotational motion, straightline motion, or static (no motion). The training medium was videotape. Soldiers in each condition were pretested and then trained on three modules comprising a total of 15 vehicles from the Basic CVI Training Program. Three training iterations were given to each condition. The first and last iteration were followed by a videotape test appropriate to the type of motion used.

### Findings:

Groups presented with vehicles in motion learned the vehicles no better after one training session than groups trained on static vehicles. After three training sessions, all groups showed further improvement. However, the rotational group improved most, while the static group improved least. Motion did not contribute to improved performance in retention over an 18-hour period

when compared with that achieved with static targets. When soldiers were divided into training responsive (TR) and non-training responsive (NTR) groups based on their performance on the first post-training test, motion did not differentially improve performance by the NTR group when compared with the TR group.

### Conclusions:

- Motion (after repeated training) provides a small positive effect but does not appear to be an essential ingredient in learning ground-to-ground vehicle R&I using the Basic CVI Training Program. This is true for both training responsive and non-training responsive soldiers.
- Short term retention of learned R&I skills is not improved when motion is included in the training.

### Utilization of Findings:

Motion is not a key requisite to improving performance in R&I. This information will be used in cost-benefit analyses of future training considerations.

# TARGET ACQUISITION AND ANALYSIS TRAINING SYSTEM: EFFECTS OF MOTION ON PERFORMANCE IN THE COMBAT VEHICLE IDENTIFICATION (CVI) TRAINING PROGRAM

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TARGET ACQUISITION AND ANALYSIS TRAINING SYSTEM: EFFECTS OF MOTION ON PERFORMANCE IN THE COMBAT VEHICLE IDENTIFICATION (CVI) TRAINING PROGRAM

### INTRODUCTION

### Background

In 1980, the Target Acquisition and Analysis Training System (TAATS), a part of the research program at the Army Research Institute's Field Unit, Fort Hood, Texas, was established. The major objective of TAATS was to provide a framework within which to do research and develop interrelated target acquisition training programs. Five have been developed, tested and turned over to the Army. They are the Basic Combat Vehicle Identification (CVI) Training Program, the Basic Thermal Combat Vehicle Identification (TCVI) Training Program, the Advanced Combat Vehicle Identification Training Program, the Flash Card Program, and the Combat Vehicle Identification Training Program for the Remotely Piloted Vehicle (RPV). Three programs, the CVI, TCVI, and Flash Cards have been adopted and issued by the Army as standard training for vehicle identification designated as GTA 17-2-9, GTA 17-2-10, and GTA 17-2-11, respectively. The Advanced CVI program awaits issue by the Army. The RPV program was used to train RPV operators for Operational Test (OT) II in June 1984.

### Military Problem

Some trainers believed that if motion were to be added to CVI training programs which use imagery, performance would be substantially improved. Certainly, motion does add realism to the extent that moving vehicles are frequently confronted and this may have a motivating effect on performance. There is no question that movement generally attracts attention. Research findings in the vehicle visual detection area (Smith, W.M., 1951; Gottsdanker, R.M., 1957; Miller, J.W., 1960; and Gutmann, J.C. et al., 1979) concluded that targets were usually more likely to be detected when in motion than when static and greatest detection occurred as the target shifted from a static to motion state when other factors such as target shape and size, contrast, clutter, etc., were held constant.

However, the objective of the CVI training programs is to teach recognition and identification (R&I)<sup>2</sup>, not detection. Merrill and Bunderson (1981, pg. 4) point out that "motion is necessary only if movement is a critical attribute required for proper discrimination." The central research question here is whether vehicle targets in motion result in better discrimination and thus significantly better soldier performance on R&I than do static vehicle targets under similar environmental conditions. If motion is not required in training to achieve improved R&I performance, costs of training materials, production, and playback systems will probably be substantially less.

<sup>&</sup>lt;sup>1</sup>A citation for the technical or research report on each of the training programs is in the Reference Section.

<sup>&</sup>lt;sup>2</sup>Detection is defined as being aware of the presence of a man-made object in the field of view; recognition is being able to call the object a friend or threat; identification is being able to give the name or number if the object is a vehicle or aircraft.

### Purpose and Scope of This Report

The major objectives of this research were to determine (1) whether introduction of motion into the Basic (VI Training Program produced better performance following initial and repeated training; (2) whether motion might facilitate learning by those soldiers who demonstrate difficulty in acquiring R&I skills; and (3) whether motion might affect retention of R&I materials after 18 hours.

### General Description

Four groups comprised of 30 soldiers each were employed. All groups were trained on (videotaped) modules 3 thru 5 (for a total of 15 vehicles) of the Army's Basic CVI Training Program (GTA 17-2-9). Each group was trained on one of four conditions: a) video rotation, b) circular motion, c) straight line motion, and d) standard static CVI images. The conditions indicated by these group designations will be explained below.

In the video rotation group, vehicles were rotated about the center of their axes, completing a 180° rotation in 7.5 seconds. The view obtained was from one full side to the other full side view. Both clockwise (CW) and counterclockwise (CCW) rotation were employed. Training was conducted showing each vehicle for a 15 second period utilizing both the CCW and CW rotations. Testing was accomplished using the CW and CCW rotations separately. In the posttraining test where the standard CVI slide sequence called for a front view, the vehicle was presented CW; where an oblique view was to be presented, the vehicle was shown CCW.

In the circular motion group, vehicles traveled through a 180° circular path in a 15 second period for the training imagery. The vehicle was seen from one full side to the other full side. Both CW and CCW movements were employed. Scaled ground speed was 8 mph. Test imagery was the same except that the vehicles traversed a 180° arc in 7.5 seconds. In order to keep the ground speed at constant 8 mph, the diameter of the arc traversed was one-half that employed in the training imagery and the speed was doubled.

For the straight line motion group, training imagery consisted of 15 second sequences with the vehicles following straight paths. Five paths were utilized. These paralleled the views seen in the standard CVI program, i.e., left side, left oblique, front, right oblique and right side. The test imagery consisted of 7.5 second views edited out of the 15 second views used for training.

In the fourth group the standard CVI reproduced on video tape was used, i.e., static images. No new imagery was required.

### Personnel

To conduct the research, 160 soldiers were requested--40 for each of the four groups. For various reasons only 120 soldiers were ultimately made available, thus reducing each group size to 30. Data from 71 soldiers met the two criteria for inclusion; 1) they were present for all training sessions and tests, and 2) they responded on all test answer sheets. Final group sizes were: Rotational 16, Circular 19, Straightline 15, and Static 21.

<sup>&</sup>lt;sup>3</sup>It is important to not that exposure time to each vehicle was held constant across all motion conditions—during training and testing.

Personnel trained were from the 1st and 3rd Brigades of the 85th Army Reserve Division (Tng) [One Station Unit Training (OSUT) 19E/19D], Arlington Heights, Illinois. In view of the large number of soldiers who failed to qualify for inclusion in subsequent analyses, it seemed prudent to examine the remaining population for potential biases.

Previous research within TAATS (Shope, et al. 1984; Smith, et al. 1986) has pointed to the probable role of GT on R&I performance. It was, therefore, judged appropriate to verify that the useable data from the final four training groups were comparable on this factor. Results of an analysis of variance of GT score for the four motion groups indicated no significant differences  $[\underline{F}(3,66)=.30,\ p=.82]$ . Means and standard deviations to support this analysis are found in Table 1.

Table 1

Mean GT Score for Each Motion Group<sup>a</sup>

Group	<u>n</u>	<u>M</u>	SD
Rotational	15	109.20	20.45
Circular	19	105.89	18.63
Straight line	15	110.87	13.34
Static	21	110.38	16.85

<sup>&</sup>lt;sup>a</sup> GT information was unavailable for one person in Rotational group.

### Procedure

Personnel were randomly assigned to seats but were asked to take the same seat for all subsequent training and testing in order to maintain image size constancy.

To insure that the three repeated training sessions could be completed in the time available following extensive orientation for the soldiers on the first day, tests after all but the first and last training sessions were omitted.

During training and testing soldiers were required to make a written response on prepared answer sheets each time a vehicle was projected. They had first to make a recognition response—F for friend, T for threat or DK (?) for "don't know." This was followed by an identification response in which the name or number of the vehicle was stated, or a DK (?) response if it could not

be identified. For example, if a Soviet T-62 were projected, the soldier should immediately write T for threat and follow it with T-62. Three modules dealing with five vehicles each were used.

In Sections A and B of each module each vehicle was presented five times for a total of 50 presentations; in section C, the Module Test, three presentations of each vehicle were shown. In the pretraining test (Test 1), static images consisting of five views of the 15 vehicles for a total of 75 responses were used. The posttraining tests (Tests 2, 3, and 4) consisted of the same number of views and vehicles as the pretraining test but using the motion on which training took place. A listing of the vehicles can be found in Appendix A.

On the morning of the second day time was allotted to test retention of the previous days knowledge after a lapsed time of 18 hours.

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The data collection schedule is presented in Table 2.

Table 2

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### Data Collection Schedule

Motion Group			16	resting/fraining Schedule									
Circular	Test 1 Pre-Tng	Tng	Test 2	Tng	Tng	Test 3	18 hours Lapsed	Test 4					

	Test			Time						
Rotational	**	**	••	**	**	**		**		
Static	**	**	••	**	••	**		••		
Straight line	••	**	**	**	**	**				

A detailed description of The Basic CVI Training Program procedure and instructions are found in GTA 17-2-9.

### Collection and Presentation Materials

A training response form was required for each module. These forms provided for responses for three presentations of five vehicles for each of the three module sections (A, B and C). In addition, the pretraining and posttraining tests required a form providing for responses to five presentations of each of the 15 vehicles. (See Appendix B)

A Soldier Reaction Questionnaire composed of 10 items was administered at the end of the research. (See Appendix C)

Five 3/4" videotape players and five 19" monitors were supplied by the 85th Division. Classrooms that would provide each of 30 soldiers with desk armchairs were used.

### Data Analysis

In order to address study objectives several analyses of variance were performed and, where appropriate, Duncan Multiple Range Tests. These statistical analyses were interpreted by use of tables and figures showing mean number of images identified.

Previous research (see references) with two dependent variables—vehicle images (slides) recognized and vehicle images (slides) identified—has reliably shown that the former is a relatively unstable measure of performance and a less sensitive measure for assessing treatment design differences. This is due primarily to the 50/50 probability of being correct if one guesses, and the consistent disregard by soldiers of the instructions which attempt to discourage guessing. For those reasons, only the number of images correctly identified was used as the dependent variable in this research.

### Development of Training Responsiveness Concept

Research conducted within the TAATS program has focused primarily on test evaluation of prototype training. In these evaluations repeated training was not given and evaluations were based on pretraining test-postraining test comparisons which, though statistically significant, left unanswered questions of suitable performance criteria, retention, and retraining. Clearly the impression that R&I is one of the more difficult skills to develop is created. More recently attention has shifted to exploring learning curves for individual soldiers when repeated training and testing are conducted. This approach has demonstrated that although some soldiers are extremely responsive to the program, other soldiers, even with repeated training, are not responsive to R&I training as currently provided in the CVI program. In order to operationalize the concept of training responsiveness as a preliminary research tool, soldiers who identified less than 50% of the vehicle images correctly on the first posttraining test were defined as non-training responsive (NTR) and those who identified 50% or more of the images were defined as training responsive (TR)4. Using this definition in the present research, 27 (38%) soldiers were considered as NTR and 44 (62%) as TR.

<sup>&</sup>lt;sup>4</sup>Previous exploratory research (Smith, et al. 1986) involving repeated training and testing indicated that this criterion resulted in significant absolute per. mance curve differences for training responsiveness groups at each training and test point. The consistency of these differences between comparable points on the performance curve for these groups was used as a basis for inferring that these groups do differ in one or more important dimensions related to R&I training.

### RESULTS<sup>5</sup>

### Effects of Motion During Training

### Pretesting Before Training

Before training began a videotaped pretest (Test 1) using 75 static vehicle images (5 views for each of 15 vehicles) was given to determine whether the knowledge of vehicles differed among soldiers assigned to groups. An analysis of variance (ANOVA) using the number of vehicle images identified as the dependent variable found that no significant differences existed  $[\underline{F}\ (3,882)\ \langle\ 1,\ p>.05]$ . Performance in this initial test was near zero, the means for the groups were as follows: circular, .55; rotational, .46; static, .70; and straightline, 1.03.

Initial Training. An ANOVA was completed on the identification performance data (number of vehicle images correctly identified) on the first posttraining test (Test 2) to determine whether or not any of the motion conditions used led to training performance differences early in learning. Results of that analysis indicated that while absolute performance of the static group was lower than for each of the other motion conditions, no significant differences among the groups were found [F(3,63) = 1.79, p = .16]. Means and standard deviations for each group on this test are found in Table 3.

Repeated Training. While performance differences among the four groups could not be detected following an initial training session, it is nevertheless relevant to ask whether motion conditions used show the same pattern of training effectiveness with repeated training. The plan was to give as many training periods as time allowed (rest periods intervening between each) during a single work day of 8 hours. Bad weather delayed the start and foreshortened the duration so that a total of only three training periods was possible. ANOVA was performed with identification performance data following the first and last training session to address this question. Results of that analysis indicated that while all groups showed improvement from Test 2 to Test 3 after repeated training, the rotational group was responsible for the greatest improvement. This accounts for the significant group by test interaction  $\{F(3,63) = 5.05, p < .01\}$ . Means and standard deviations to support this analysis are also presented in Table 3 and graphically depicted in Figure 1. Inspection of these data suggests that with repeated training, rotational motion of vehicles results in substantially greater improvement in performance compared to other motion conditions (including the static no-motion group).

Finally, a separate ANOVA of only Test 3 identification performance data was performed. It indicated significant differences among the groups  $[\underline{F}(3,63) = 5.77, \underline{p} < .01]$ . A Duncan Multiple Range Test for these means indicated that while differences existed among non-static motion conditions, performance in the Static condition was significantly lower than for all other motion conditions  $(\underline{p} < .05)$ . Complete results of this test are summarized in Table 3.

 $<sup>^{5}\</sup>mathrm{A}$  summary of the sources of variance for all ANOVAs is found at Appendix D.

Table 3

Means and Standard Peviations of Number of Images Identified for Each Motion
Group on Test 2 and Test 3

			Te	sts		
		Test	: 2	Test 3 <sup>a</sup>		
Motion Group	n	M	SD	M	SD	
Circular	19	46.21	17.42	58.11 <sup>a</sup>	19.88	
Rotational	16	42.81	19.02	65.31 <sup>b</sup>	9.22	
Static	21	36.81	21.26	50.71 <sup>c</sup>	21.11	
Straightline	15	51.00	21.04	63.60 <sup>ab</sup>	12.84	

<sup>&</sup>lt;sup>a</sup>Means with the same superscript on Test 3 are not significantly different (p > .05) according to the results of a Duncan Multiple Range Test; because results reported in the first paragraph of this section (for Test 2) indicate no significant differences among motion conditions, no further testing on mean differences was statistically appropriate.

### Motion and Training Responsiveness

Effects of Motion on Training Responsiveness. As discussed in a previous section, exploratory analyses of performance data collected in previous research determined that the large variance in performance could be accounted for by particular soldiers who manifest an inability or unwillingness to learn this material. These findings were further explored in this research. The division of the sample population was made empirically after examination of the data—all soldiers who scored 50% or more correctly on the first posttraining test were labeled training receptive (TR) and those below 50% as non-training receptive (NTR).

To first determine whether there was an overall performance difference between the TR and NTR groups for each of the four motion conditions, an ANOVA of their identification performance scores (number of vehicle images identified) after three training periods was done. Results of that analysis indicated no overall differences existed  $[\underline{F}(3,63) = 2.01, p > .05]$ .

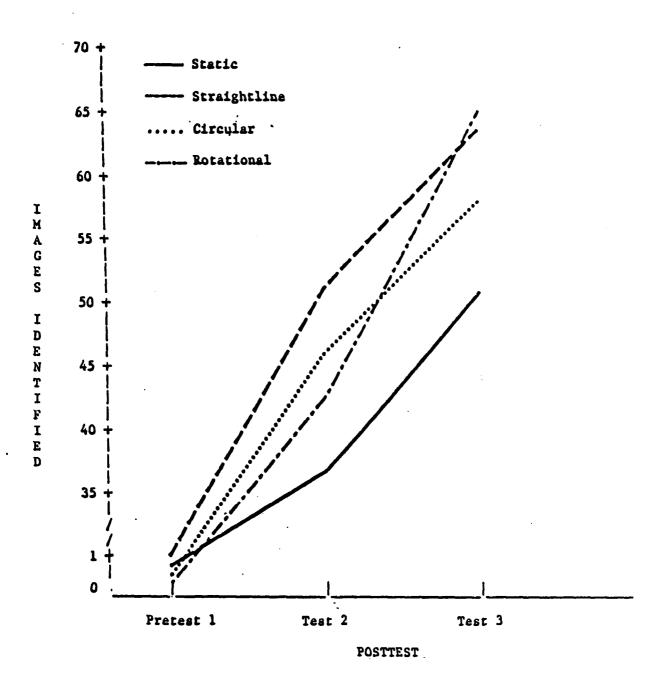


Figure 1. Mean Number of Vehicle Images Identified on Pretraining Test and Posttraining Tests (T2, T3) by Motion Group After Two Additional Training Trials

Effects of Motion and Repeated Training on Training Responsiveness. As just noted, there were no overall significant differences among training responsiveness groups to different motion training conditions. It did seem relevant however, to ask whether both training responsiveness groups showed the same pattern of differences to different training conditions after one and three training sessions. Results of an analysis of variance involving these three variables (motion type, training responsiveness group and test period) indicated that indeed significant differences did exist [F(3,63) = 6.18, p]<.01]. Table 4 presents supporting means and standard deviations; Figure 2 portrays this relationship pictorially. These data show that this significant difference probably can be attributed to the fact that the NTR soldiers in the rotational and straightline motion conditions show large increases in performance after receiving two additional training sessions. The inference can be drawn that if additional training time is available, training with motion might be useful for soldiers who experience difficulty in acquiring R&I skills (NTR soldiers).

To investigate further the inference noted above, four additional simple analyses of variance were performed. These analyses involved comparison of performance to each motion condition for only: 1) TR soldiers after the first training session; 2) TR soldiers after the third training session; 3) NTR soldiers after the first training session; and 4) NTR soldiers after the third training session. Analyses for TR soldiers indicated no significant performance differences among motion conditions [F(3,90) < 1] following either one or three training sessions. For NTR soldiers performance following the first training sessions showed no significant performance differences among motion conditions [F(3,23) < 1]. For the NTR soldiers there were significant performance differences among motion conditions following the third training session [ $\underline{F}(3,23) = 6.50$ , p<.005]. A Duncan Multiple Range Test for NTR soldier performance following the third training session revealed that performance to the Rotational motion condition was superior to all other training conditions (p<.05); no significant differences existed among any remaining training conditions for these soldiers.

### Effects of Motion on R&I Performance With Individual Vehicles

While different motion conditions did not produce overall significant performance differences during initial training (as noted above), it was nevertheless relevant to expect that for some vehicles, motion might facilitate learning. An ANOVA of number of vehicle images correctly identified on the first posttraining test (Test 2), however, indicated no significant difference  $[\underline{F}(42,882)=1.37,\ p=.06]$ . A comparable analysis on the test performance after the last training session was, however, significant  $[\underline{F}(42,882)=1.70,\ p<<.01]$ . See Appendix E for means, standard deviations and the Duncan Multiple Range Test analysis.

Means and Standard Deviations of Number of Vehicle Images Identified for Each Motion and Training Responsiveness Group After One and Three Training Sessions

Motion	Training		Te	st 2	Test	: 3
Group	Responsiveness	<u>n</u>	<u>m</u>	<u>SD</u>	<u>M</u>	<u>SD</u>
011	TR	11	58.27	12.00	71.27	6.18
Circular	NTR	8	29.62	5.58	40.00	17.74
	TR	10	55.30	9.99	68.90	9.75
Rotational	NTR	6	22.00	8.60	59.33	3.93
	TR	11	53.64	12.72	68.27	6.23
Static	NTR	10	18.30	9.90	31.40	12.47
	TR	12	59.33	11.92	68.08	4.06
Straightline	NTR	3	17.67	15.31	45.67	20.60

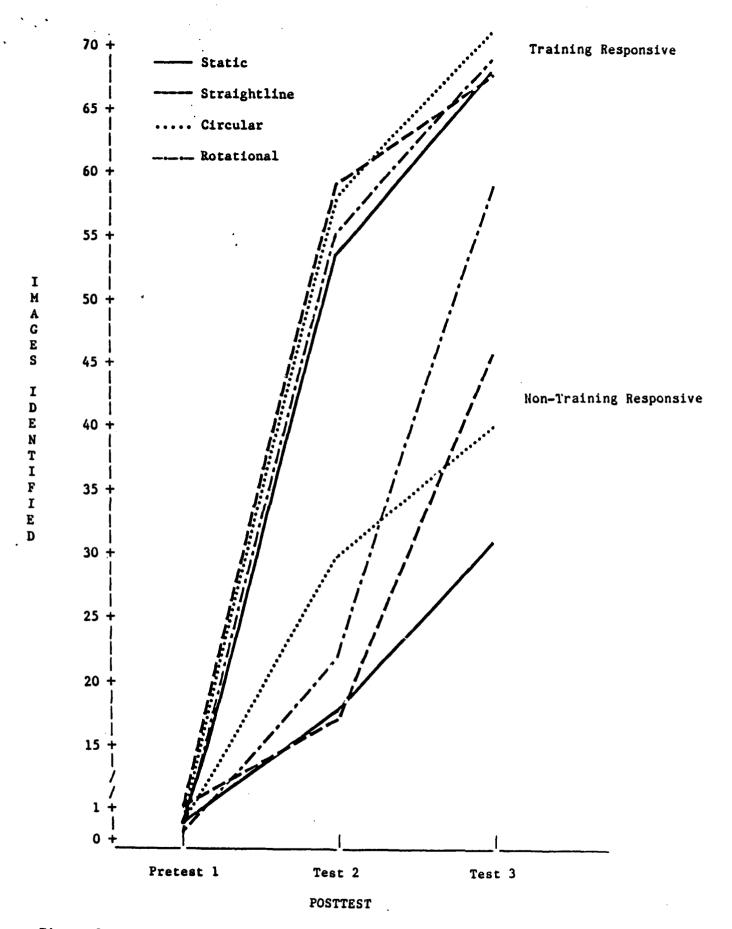


Figure 2. Mean Number of Vehicle Images Identified on Pretraining Test and Posttraining Tests (T2, T3) by Motion and Training Responsiveness Group (TR and NTR)

### Effect of Motion on Retention

The amount of learning which was retained after an eighteen hour lapse of time was examined by comparing scores received on the test given after the last training session (the last test administered after completion of training on one day) with scores from a test administered eighteen hours later. An ANOVA of number of images identified over these two tests was performed with four motion groups, two training responsiveness groups and 15 vehicles included as design variables. Results of that analysis indicated no significant differences in retention among motion conditions  $[\underline{F}(3,63) = 1.23, p > .05]$  and no significant retention differences as a function of both motion and training responsiveness conditions [F(3,63) = 2.40, p > .05].

### Soldier Reaction Questionnaire

The responses to the questions on the Soldier Reaction Questionnaire were generally positive. In response to how effective or ineffective the soldiers had found the training, 95% thought circular motion to be either "very effective" or "effective," 89% gave Rotational Motion a similar rating, approximately 73% found Straightline Motion training to be either "very effective" or "effective," and 68% found static image training to be "very effective" or "effective." When asked how this training compared with previous combat vehicle identification training they had received, approximately 91% indicated it was "much" or "somewhat" better. Frequencies supporting these conclusions are presented in Table 5.

### Characteristics of TR and NTR Soldiers

In order to better understand the dimensions characterizing TR and NTR soldiers, and in order to assure that the effects of motion conditions and training responsiveness were not confounded, a Chi-square analysis of the distribution of TR/NTR soldiers across motion groups was performed. Results of that analysis were non-significant. See Appendix D2. This finding is consistent with the inference that TR and NTR soldiers were generally distributed in about the same proportion in each motion treatment. Review of data in Appendix D2, Table 1 indicates NTR soldiers were between 21% and 47% of the sample in each motion group. To further examine the dimensions characterizing TR and NTR soldiers, additional Chi-square analyses were performed using the three GT groupings (<90, 90-109, 110 and up) which produced a significant  $X^2 = 13.66$ , p < .001 on 2 degrees of freedom (See Appendix F3). Inspection of the table in Appendix F3 suggests that this significant relationship is due to the disproportionately large number of TR soldiers with GT > 109. Using ranks comprising Skill Level 1 (pay grades E1-E4) vs higher skill levels (pay grades E5-E8) and time in service arbitrarily grouped by years, soldiers were found to be proportionately distributed in TR and NTR groups,  $X^2 = 2.20$ , p = .65 on 1 degree of freedom,  $X^2 = 1.34$ , p = .93 on 5 degrees of freedom, respectively (See pages F4 and F5).

Table 5
Soldier Reaction Questionnaire Responses

		Responses									
	<u>n</u>	2	<u>n</u>	x	<u>n</u>	z	<u>n</u>	z	ņ	x	
		lery fective	Eff	ective	aI	Between	Inef	fective		Very fective	
How effective/ineffective was the training using straight line motion for you?	14	35.00	15	37.50	9	22.50	2	5.00	0	0.00	
How effective/ineffective was the training using circular motion for you?	21	53.85	16	41.03	2	11.43	0	0.00	0	0.00	
How effective/ineffective was the training using rotational motion for you?	16	45.71	15	42.86	4	11.43	0	0.00	0	0.00	
How effective/ineffective was the training using stationary motion for you?	7	18.42	19	50.00	10	26.32	2	5.26	0	0.00	

cont'd

Table 5 (continued)

Soldier Reaction Questionnaire Responses

					Res	ponses				
	<u>n</u>	x	ņ	x	<u>n</u>	*	<u>n</u>	x	<u>n</u>	;
		Huch Better	_	omewhat Better	The	e Same		omewhat Jorse	Mu Wo	ch rse
Compared with other training in vehicle recognition how would you evaluate the training you have just received?	35	55.56	22	34.93	3	4.76	3	4.76	O	0.00
					Yes			No		
Are you familiar with the Basic CVI Training Program?					38	55.88		30	44.12	
Are you familiar with the Thermal Training Program?					4	7.27		51	92.73	
Did you participate in the CVI training given in January?					26	38.24		42	61.77	

### DISCUSSION

### Discussion

During the development of the CVI program an hypothesis evolved which held that if motion were added to training programs using static imagery, performance would be substantially improved. Realism (training fidelity) and motivational effects caused by increased interest may be part of the reason for this presumed improvement in performance; however, it seems appropriate to use movement (motion) only when it is a critical attribute which facilitates improved training performance.

Results of this research have indicated that during initial training, motion does not generally appear to contribute significantly to identification performance compared to presentation of static images. While repeated training with motion did result in statistically significant overall performance differences compared to the static (no motion) condition, the improvement seems to be of little practical significance. Table 6 shows that the proportion of variability in the data accounted for by motion is only about 3%. Further, while motion did appear to significantly increase identification performance with the AMX30 and PT76 after repeated training, the proportion of variability in the data accounted for by motion and vehicles is only slightly over 1% (See Table 6). Finally, while use of motion did tend to significantly reduce performance differences between TR and NTR soldiers with repeated training, the proportion of variability accounted for by this relationship was only a little over 3% (See Table 6).

Table 6 Use of the  $\omega^2$  Statistic to Estimate the Proportion of Variance Accounted for by Each ANOVA Effect Using Posttest Data Obtained Following the Third Training Session<sup>a</sup>

	Effect	<u>ω</u> 2	
Moti	on Group (G)	.032	
Trai	ning Responsiveness (T)	.208	
	cle (V)	.068	
G x	T	.033	
G x	V	.012	
Τx	V	.025	
G x	T x V	.008	

<sup>&</sup>lt;sup>a</sup> The proportion of variance accounted for by each effect is estimated by a generalization of formulas presented by Hays, Statistics, p.407 by

In addition to the weakness of the training responsiveness and motion relationship after repeated training, it is relevant to consider absolute performance levels attained by NTR soldiers compared to TR soldiers. In most cases average performance of NTR soldiers after three training sessions does not reach the level attained by TR soldiers after a single training session. This raises two questions of some interest to the training community: (1) Should all soldiers be required to be proficient in R&I? (2) If so, since motion does not add significantly to their performance, what medium would be required and would it be cost-effective to use it?

Finally, it appears that motion contributes nothing to either group's (NTR, TR) short term memory.

### CONCLUSIONS

- Motion (after repeated training) provides a small positive effect but does not appear to be an essential ingredient in training ground-to-ground vehicle R&I using the Basic CVI Training Program. This is true for both training responsive and non-training responsive soldiers.
- Short term R&I retention is not improved when motion is included in the training.

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### APPENDIX A

List of Vehicles Used in Training

Table 1
Vehicles Used for All Groups

	····	
M48	3	MARDER
SAI		T72
251	J23 <b>–</b> 4	CHIEFTAN
вт	R 50	zsu57-2
AM	K 30	JAGD
PT	76	T54/55
Sc	imitar	ROLAND
M1		

### APPENDIX B

### Data Collection Instruments

- 1. Pre/Post-Test
- 2. Example of Training Response Sheets for one type of motion, Straightline. All others are the same.

### DATA REQUIRED BY THE PRIVACY ACT OF 1974

TITLE OF FORM Basic Combat Vehicle Identification (CVI)
Training Program - Soldier Information

PRESCRIBING DIRECTIVE
AR 70-1

1. AUTHORITY

10 USC Sec 4503

### 2. PRINCIPAL PURPOSE(S)

The data collected with the attached form are to be used for research purposes only.

### 3. ROUTINE USES

This is an experimental personnel data collection form developed by the U.S. Army Research Institute for the Behavioral and Social Sciences pursuant to its research mission as prescribed in AR 70-1. When identifier (name or Social Security Number) are requested they are to be used for administrative and statistical control purposes only. Full confidentiality of the responses will be maintained in the processing of these data.

FORM

Privacy Act Statement - 26 Sep 75

<sup>4.</sup> MANDATORY OR VOLUNTARY DISCLOSURE AND EFFECT ON INDIVIDUAL NOT PROVIDING INFORMATION
Your participation in this research is strictly voluntary. Individuals are
encouraged to provide complete and accurate information in the interests of
the research, but there will be no effect on individuals for not providing
all or any part of the information. This notice may be detached from the
rest of the form and retained by the individual if so desired.

DATE		
MODULE	NO.	
SEAT #		
RANGE		

### BASIC COMBAT VEHICLE IDENTIFICATION (CVI) TRAINING PROGRAM

### MODULE 7

### SOLDIER INFORMATION

Τ.	Hame.					
		(Last)		(First)		
2.	Rank:		····	3	. SSN:	
4.	Age: _	· · · · · · · · · · · · · · · · · · ·	5. Mi	litary Unit:		· · · · · · · · · · · · · · · · · · ·
6.	Time i	n Service:				
		in Service:	(Years)	(Mon	ths)	
7.	MOS: _				<del></del>	
8.	Length	of time in	MOS:	ears)	(1)	donths)
9.	What i	s the MOS o	f the job to	o which you	are curi	rently assigned?
10.	Do you	wear glass	es (or cont	act lenses)	on the	job?
	Yes _		No			
10a.	Do you	wear glass	es (or cont	act lenses)	only for	r reading?
	Yes _		No	<u>.</u>		

MACT	TON	STUD	ı
14:1 1:41	I DIN	<b>NIII</b>	7

PRE	<b>/POS</b>	TTE	57

Date:	
Row No. Seat No. Range	

Name	Ł	Rank	
Unit			

Treatment:	
------------	--

<u>No</u> .	Friend/ Threat	Name/ Model	<u>No</u> .	Friend/ Threat	Name/ Mode l
1			27		
2			28		
3			29		
4	<del></del>		30		
5			31		<del></del>
6			32		
7	<del></del>		33		
8			34		
9			35		
10			36		
11			37		
12			38		
13			39		
14			40		
15	<del></del>		41		
16			42		
17			43		
18	<del></del>		44		
19			45		
20			46		
21			47		
22			48		<del></del>
23			49		<del></del>
24		-	50	<del></del>	<del></del>
25	<del></del>		51	<del></del>	
26			51 52		
20		<del></del>	52		<del></del>

	Friend/	Name/		Friend/	Name/
<u>No</u> .	Threat	<u>Model</u>	No.	Threat	Mode 1
53			64	<del></del>	
54			65		
55			66		
56			67		
57			68		
58			69		
59			70		
60			71		
61			72		
62			73		
63			74		
_			75		

### MOTION STUDY

## MODULE 3

Date:	
Row No.	
Seat No.	
Range	

# Straightline Motion Training Worksheet

Name & Rank \_\_\_\_\_

Unit				<del></del>	
		Section A: Vide	o Presentation	Sequence	
No.	Friend/ Threat	Name/ Model	No.	Friend/ Threat	Name/ Model
D-1			D-14		
D <b>-</b> 2			 15		
D-3			D-16		
4			D-17	<del></del>	
D-5			 18		
6			 D-19		
D-7	<del></del>		 D-20		<del></del>
D-8			 D-21		
D <b>-</b> 9					
D-10			D-23		
0-11			D_24		
D-12	<del></del>		D-25		
D-13					
			<del></del>		
		Section B: Vide	o Presentation	Sequence	
D-26			39		
D-27			D-40		
28			41	,	
D-29			D-42		
D-30			D-43		
0-31			D-44	<del></del>	
32			 D-45		
D-33			D-46		
D-34	<del></del>		D-47		
D-35	<del></del> ·		D-48		
n-36			D-49		<del></del>
D-37		·····			<del></del>
D-38	<del></del>				<del></del>

#### MODULE 3

Kow	No.	
Seat	No.	
Rang	je	

#### STRAIGHTLINE MOTION TEST ANSWER SHEET

Name	&	Rank	
MOS			Unit

# Section C: Module Test (7.5 second exposure)

No.	Friend/Threat	Name/Model
1		
2	•	
3	<del></del>	
4	<del></del>	
5		
6	<del></del>	
7		
8	<del></del>	
9	<b></b>	
10	<del></del>	
11		
12	-	
13	<del></del>	
14	<del></del>	
15		

#### APPENDIX C

Soldier Reaction Questionnaire

#### SOLDIER REACTIONS

Motion Test 85th Div 22-23 Oct 1983

Name			Rank/GS		
Orga	nization			<del></del>	
Posi		escription			·
					<del></del>
1.	How realistic	- unrealistic	was the straight	line motion yo	ou observed?
ı	ł	Į	1		ŧ
·.	Very Realistic	Realistic	Neither Realistic nor Unrealistic	Unrealistic	Very Unrealistic
2.	How realistic	- unrealistic	was the circular	motion you obs	served?
<b> </b>	Very Realistic	Realistic	Neither Realistic nor Unrealistic	Unrealistic	Very Unrealistic
3.	How realistic	- unrealistic	was the rotation	nal motion you	observed?
	1		1	1	
	Very Realistic	Realistic	Neither Realistic nor Unrealistic	Unrealistic	Very Unrealistic
			r 4 was other the		
5.	Did you part:	icipate in the	CVI training giv	en in January o	f this year.
6. the		n other trainin have just rece		ognition how wo	uld you evaluate
1		1			
	Much Better han Previous Training	Better Than	About The Same	Poor Than	Much Poorer Than Previous Training

<ul><li>llow effective ou?</li></ul>	/ineffective was	s the training (	using straight :	line motion for
			<u> </u>	<u> </u>
Very Effective	Effective	In Between	Ineffective	Very Ineffective
. How effective	e/ineffective wa	s the training	using circular i	motion for you
Very Effective	Effective	In Between	Ineffective	Very Ineffective
. How effective ou?	e/ineffective wa	s the training	using rotationa	l motion for
L	1		<b></b>	<u> </u>
Very Effective	Effective	In Between	Ineffective	Very Ineffective
). How effectivou?	ve/ineffective w	as the training	using stationa	ry vehicles fo
			<u> </u>	ļ <u>-</u>
Very Effective	Effective	In Between	Ineffective	Very Ineffective
l. Are you fam:	iliar with the o	current vehicle	training progra	ms in the Army
GTA 17-2-9 GTA 17-2-10		( ) Yes ( ) N ( ) Yes ( ) N		

#### APPENDIX D

Sources of Variance for all ANOVAs

Table 1

Analysis of Variance of Number of Vehicle Images Identified Following the Initial and Third Training Session for Soldiers Participating in the Motion Study

				~~~~~~~~	
sv	df	ss	<u>ms</u>	<u>F</u>	<u>P</u>
Between Soldiers (S)	70	2582.32			
Motion (M)	3	102.16	34.06	3.21	<.05
Training Respons- iveness (R)	1	1747.74	1747.74	164.73	<.001
MR	3	63.88	21.29	2.01	>.05
S/MR	63	668.54	10.61		
Within Ss	2059	5272.57			
Test (T)	1	589.03	589.03	147.63	<.001
Vehicle (V)	14	705.49	50.39	24.88	<.001
TV	14	134.51	9.61	8.08	<.001
MT	3	60.43	20.14	5.05	<.005
MV	42	151.78	3.61	1.78	<.01
MTV	42	50.69	1.21	1.02	>.05
RT	1	46.08	46.08	11.55	<.01
RV	14	137.72	9.84	4.85	<.01
RTV	14	41.10	2.94	2.47	<.01
MRT	3	74.01	24.67	6.18	<.01
MRV	42	140.82	3.35	1.65	<.01
MRTV	42	52.73	1.26	1.06	>.05
ST/MR	63	251.11	3.99		
SV/MR	882	1786.44	2.03		
STV/MR	882	1050.63	. 1.19		

Table 2

Analysis of Variance of Number of Vehicle Images Identified During the Initial Posttest for Soldiers Participating in the Motion Study

sv	df	<u>ss</u>	MS	<u>F</u>	<u>P</u>
Between Soldiers (S)	70 ·	1755.78			
Motion (M)	3	42.41	14.14	1.79	>.05
Training Respons- iveness (R)	1	1197.18	1197.18	151.69	<.001
MR	3	18.98	6.33	<1	>.05
S/MR	63	497.21	7.89		
Within Ss	994	2686.18			
Vehicle (V)	14	616.48	44.03	22.15	<.001
MV	42	114.49	2.73	1.37	>.05
RV	14	85.09	6.08	3.06	<.001
MRV	42	116.95	2.78	1.40	<.05
SV/MR	882	1753.17	1.99		

Table 3

Analysis of Variance of Number of Vehicle Images Identified Following the Third Training Session for Soldiers Participating in the Motion Study

sv	df	<u>ss</u>	MS	F	<u>P</u>	
Between Soldiers (S)	70 ·	1292.33				
Motion (M)	3	116.15	38.72	5.77	<.01	
Training Responsiveness (R)	1	634.82	634.82	94.67	<.001	
MR	3	118.92	39.64	5.91	<.01	
S/MR	63	422.44	6.71			
Within Ss	994	1565.75				
Vehicle (V)	14	223.53	15.97	12.99	<.001	
MV	42	87.99	2.10	1.70	<.005	
RV	14	93.73	6.70	5.45	<.001	
MRV	42	76.60	1.82	1.48	<.05	
SV/MR	882	1083.90	1.23			

Table 4

Analysis of Variance of Number of Vehicle Images Identified Following the Third Training Session and a Retention Test the Following Day for Soldiers Participating in the Motion Study

sv	df	<u>ss</u>	MS	<u>F</u>	<u>P</u>
Between Soldiers (S)	70	2655.07			
Motion (M)	3	229.98	76.66	5.65	<.005
Training Responsiveness (R)	,	1201 22	1201 22	05.04	( 00)
	1	1301.33	1301.33	95.94	<.001
MR	3	269.25	89.75	6.62	<.001
S/MR	63	854.51	13.56		
Within Ss	2059	3422.39			
Test (T)	1	3.82	3.82	2.21	>.05
Vehicle (V)	14	400.94	28.64	14.39	<.001
TV	14	15.00	1.07	1.73	>.05
MT	3	6.41	2.14	1.23	>.05
MV	42	176.82	4.21	2.12	<.001
MTV	42	36.52	.87	1.40	>.05
RT	1	1.12	1.12	<1	>.05
RV	14	163.70	11.69	5.87	<.001
RTV	14	7.35	.52	<1	>.05
MRT	3	12.49	4.16	2.40	>.05
MRV	42	157.15	3.74	1.88	<.01
MRTV	42	34.43	.82	1.32	>.05
ST/MR	63	109.10	1.73		
SV/MR	882	1752.85	1.99		
STV/MR	882	544.69	.62		

Table 5

Analysis of Variance of the Number of Vehicle Images Identified During the Pretest for Soldiers Participating in the Motion Study

<u>sv</u>	df	<u>ss</u>	MS	<u>F</u>	<u>P</u>
Between Soldiers (Ss)	70	1006.18			
Motion (M)	3	18.05	6.02	<1	>.05
Training Responsiveness (R)	1	200.85	200.85	16.21	<.0002
MR	3	6.88	2.29	<1	>.05
S/MR	63	780.40	12.39		
Within Ss	994	1169.24			
Vehicle (V)	14	162.34	11.60	11.83	<.0001
MV	42	38.85	.93	<1	>.05
RV	14	66.95	4.78	4.88	<.0001
MRV	42	36.35	.87	<1	>.05
SV/MR	882	864.75	.98		

#### APPENDIX E

Means, Standard Deviations, and Duncan Multiple Range Test Analysis for Vehicles

Means and Standard Deviation of Number of Vehicle Images Identified for Each Vehicle in Each Motion Condition After the Third Training Session<sup>a</sup>

<u>Vehicle</u>		Static	Motion Rotational	Condition Circular	Straightline
<b>140</b>	<u>M</u>	3.48 <sub>a</sub>	4.50 <sub>b</sub>	4.53 <sub>b</sub>	4.20 <sub>ab</sub>
M48	SD	1.75	.73	1.02	1.57
SALADIN	<u>M</u>	3.38 <sub>a</sub>	4.75 <sub>b</sub>	4.11 <sub>ab</sub>	4.33 <sub>b</sub>
SALADIN	SD	2.01	.77	1.88	.62
ZSU23-4	<u>M</u>	2.14 <sub>a</sub>	3.94 <sub>c</sub>	2.89 <sub>b</sub>	3.40 <sub>bc</sub>
23023-4	SD	2.37	1.73	2.26	1.76
BTR 50	<u>M</u>	2.90 <sub>a</sub>	3.63 <sub>ab</sub>	3.00 <sub>a</sub>	4.00 <sub>b</sub>
BIR 30	<u>SD</u>	2.21	1.67	2.29	2.07
AMX 30	<u>M</u>	2.33 <sub>a</sub>	3.81 <sub>b</sub>	3.21 <sub>b</sub>	3.20 <sub>b</sub>
AM 30	<u>SD</u>	2.20	1.56	2.23	1.61
PT76	<u>M</u>	3.05 <sub>a</sub>	4.31 <sub>b</sub>	4.11 <sub>b</sub>	4.40 <sub>b</sub>
	<u>SD</u>	2.13	1.35	1.37	.51
Scimitar	M	3.43 <sub>a</sub>	4.34 <sub>bc</sub>	3.68 <sub>ab</sub>	4.67 <sub>c</sub>
SCIMICAL	<u>SD</u>	1.83	1.09	2.06	.49
MARDER	<u>M</u>	3.67 <sub>a</sub>	4.94 <sub>b</sub>	4.11 <sub>ab</sub>	4.40 <sub>b</sub>
PARDER	SD	2.06	.25	1.76	.63
т72	<u>M</u>	3.05 <sub>a</sub>	4.13 <sub>b</sub>	3.89 <sub>ab</sub>	4.33 <sub>b</sub>
	<u>SD</u>	2.09	1.09	1.66	1.11
CHIEFTAN	<u>M</u>	3.62 <sub>a</sub>	4.81 <sub>b</sub>	4.47 <sub>ab</sub>	4.53 <sub>c</sub>
CHIEFIAN	<u>SD</u>	1.60	.40	.96	.92

Means and Standard Deviation of Number of Vehicle Images Identified for Vehicle in Each Motion Condition After the Third Training Session<sup>a</sup>

Table 1 (cont'd)

<u>Vehicle</u>		Static	Motion Rotational	Condition Circular	Straightline
	<u>M</u>	3.24 <sub>a</sub>	4.50 <sub>bc</sub>	3.63 <sub>ab</sub>	4.53 <sub>c</sub>
2SU57 <b>-</b> 2	SD	2.14	1.10	1.80	1.13
I.OD	M	4.43 <sub>a</sub>	4.81 <sub>a</sub>	3.89 <sub>a</sub>	4.13 <sub>a</sub>
JAGD	SD	1.21	.54	2.00	1.77
T54/55	M	3.38 <sub>a</sub>	3.69 <sub>a</sub>	3.79 <sub>a</sub>	4.20 <sub>a</sub>
	<u>SD</u>	1.77	1.70	1.81	1.15
ROLAND	<u>M</u>	4.81 <sub>a</sub>	4.50 <sub>a</sub>	4.42 <sub>a</sub>	4.87 <sub>a</sub>
	<u>SD</u>	.68	.89	1.35	.52
Ml	<u>M</u>	3.81 <sub>a</sub>	4.63 <sub>a</sub>	4.37 <sub>a</sub>	4.40 <sub>a</sub>
	SD	1.69	1.09	1.30	1.59

<sup>&</sup>lt;sup>a</sup>Means followed by the same letter for a <u>given</u> vehicle are not significantly different according to the Duncan Multiple Range Test ( $\underline{p} > .05$ ). Statistical differences <u>between</u> vehicles are not reported.

#### APPENDIX F

Chi-Square Analyses of TR and NTR Groups by Background Variables

Table 1. CHI-SQUARE ANALYSIS OF TRAINING AND NON-TRAINING RESPONSIVENESS MOITON CMA

Train	Group					
Frequency Percent Row PCT COL Pct	Circular	Rotational	   Static	   Straight	   Total	
Non-	8	6	10	3	27	
i	11.27	8.45	14.08	1 4.23	38.03	
	29.63	22.22	1 37.04	1 11.11	i	
_	42.11	37.50	47.62	20.00	į	
Resp	11	10	11	12	1 44	
	15.49	14.08	15.49	16.90	61.97	
	25.00	1 22.73	25.00	27.27	1	
	57.89	62.50	52.38	1 80.00	1	
TOTAL	19	16	21	14	71	
	26.76	22.54	29.58	21.13	100.00	
CHI-SQUARE		3.024	DF - 3	Prob = 0.38	79	

Table 2. CHI-SQUARE ANALYSIS OF TRAINING AND NON-TRAINING RESPONSIVENESS BY CT

- I	Under 90	90 - 109	Over 109	TOTAL
. 0	9	9	9	27
- 1	12.86	12.86	1 12.86 1	38.57
<b>-</b> i	33.33	33.33	33.33	
-	81.82	47.37	22.50	
1	1 2	10	31	43
-	2.86	14.29	1 44.29	61.43
-	4.65	23.26	1 72.09 1	
-	18.18	52.63	1 77.50	
	11	19	40	70
•	15.71	27.14	57.14	100.00
	-	0   9 -   12.86 -   33.33 -   81.82 -   2.86 -   4.65 -   18.18	0   9   9 -   12.86   12.86 -   33.33   33.33 -   81.82   47.37 1   2   10 -   2.86   14.29 -   4.65   23.26 -   18.18   52.63 -   11   19	0   9   9   9   9   9   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86   12.86

Chi-Square

13.664

DF = 2 Prob = 0.0011

Table 3. CHI-SQUARE ANALYSIS OF TRAINING AND NON-TRAINING RESPONSIVENESS BY RANK

	Train	Rank				
	Prequency   Percent   Now PCT   Col Pct   Non-	E1-E4	E5-E8	Total		
		10 14.08 37.04 41.67	17   23.94   62.96   36.17	27 38.03		
	Resp	14 19.72 31.82 58.33	1 30     42.25     68.18     63.83	44 61.97		
	Total	24 33.80	47 66.20	71 100.00		
Chi-Square		0.204	DP = 1	Prob = 0.6518		

Table 4. CHI-SQUARE ANALYSIS OF TRAINING AND NON-TRAINING RESPONSIVENESS BY SERVICE TIME

Train	1	Servtine						
Frequency Percent Now Pct Col Pct	-	  Up to 1 yr	  1+ to 2 yrs	  2+ to 3 yrs	  3+ to 4 yrs	  4+ to 5 yrs	  Over 5 yrs	Total
Non-	-	0.00	2 . 90 7 . 69 25 . 00	2   2.90   7.69   40.00	3   4.35   11.54   42.86	3   4.35   11.54   37.50	16   23.19   61.54   40.00	26 37.69
Resp	1 -	1 1.45 2.33 100.00	8.70 13.95 75.00	1 4.35 1 6.98 1 60.00	5.80 9.30 57.14	7.25 1 11.63 62.50	24 34.78 55.81 60.00	43 62.33 1
TOTAL	-	1 1.45	8 11.59	5 7.25	7 10.14	8 11.59	40 57.97	69 100.00

Chi-Square 1.336 DF = 5 Prob = 0.9312